////////////////////////VIDEO OVERVIEW//////////////////////////////

Connecting MAVProxy to our SITL drone

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Commands used in this video:

New way to start sitl:

courseRoot/apm/ardupilot/build/sitl/bin/arducopter --model copter

(This will start the drone, but will not load any default parameters

or configuration. To load in default parameters/configs use the following

command:

./arducopter -S -I0 --home -35.363261,149.165230,584,353 --model "+" --speedup 1 --defaults /home/ardupilot/Tools/autotest/default\_params/copter.parm

)

Connect MAVProxy to sitl manually:

mavproxy.py --master tcp:127.0.0.1:5760